

# A Gravitational Base Energy Sensitive Energy Hierarchical Protocol (GESEHP) for Clustered Heterogeneous WSNs

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Abstract-In WSN, CH selection and routing are 2 well-known major issues for reducing their life time increasing number of dead nodes which depend on supervision of the energy saving in each sensor Node associated with high computational complexity. Many algorithms have been developing but best but clustering base algorithms were escalation lot of significance in declining the network sensor number of dead nodes of each network. This research paper proposed “A Gravitational Energy Sensitive Energy Hierarchical Protocol” (GESEHP) protocol technique in which every sensor node has energy levels of heterogeneity ordered network which autonomously selects itself as a CH based on its primary energy comparative to that of further nodes. The network life was increased as compared. This work will be analysis and simulation will be run by using different-different case in which we put the value of Node Inner Energy 0.2, 0.5, 0.9 J and Node Inner Energy 2J. In this experiment examination cases have been careful in this learning for performance assessment. The proposed algorithm will be test with some of the existing related techniques. This work is decided that our protocol GESEHP will attain improved results in small as well as large sized networks.

**Keywords-** Gravitational, Efficiency, Throughput, unicast, network, L-LEACH, Quality of Service, W-LEACH, broadcast packet, routing protocol, Energy Sensitive, IEEE 802.11,.

## I. INTRODUCTION

In the sensor nodes non-rechargeable batteries help to run, so along with efficient routing the network should be energy effective with efficient use of the resources and hence this is an important research concern. Wireless Sensor Networks (WSNs) have been broadly taken in account as a standout amongst the most vital advancements for the twenty first century [1]. Empowered by late advances in remote communication advances, little, modest, and shrewd sensors sent in a physical range and organized through remote connections and the Internet give extraordinary chances to an assortment of nonmilitary personnel and military applications, for instance, natural supervision, war zone observation and control of industrial process [2]. Recognized from conventional remote communication systems, for instance, cell frameworks and mobile ad hoc networks (MANET), WSNs have one of a kind qualities, for instance, denser level of hub organization, higher lack of quality of sensor hubs and extreme vitality, calculation, and capacity imperatives [3], which display numerous new difficulties in the improvement and use of WSN. In the previous decade, wireless sensor networks have gotten gigantic consideration from both scholarly world and industry everywhere throughout the world. A lot of research exercises have been

completed to investigate and settle different plan and application issues and huge advances have been made in the improvement and deployment of wireless sensor networks. It is imagined that sooner rather than later wireless sensor networks will be broadly utilized as a part of various regular citizen and military fields and alter the way we live, work, and collaborate with the physical world [4].

A WSN regularly comprises of a substantial number of low cost, low control and multifunctional sensor hubs that are conveyed in an area of intrigue. These sensor hubs are little in estimate, however are outfitted with sensors, implanted microchips and radio handsets and in this manner have detecting capacity, as well as information preparing and imparting abilities. They convey over a short separation by means of a remote medium and team up to achieve a typical errand, for instance, condition observing, front line observation, and mechanical process control. Remote sensors have critical points of interest over traditional wired sensors [5]. They cannot just diminish the cost and deferral in arrangement; additionally it can be connected to any condition, particularly those in which customary wired sensor systems are difficult to be deployed, for instance, unwelcoming territories, war zones, space or profound seas. Wireless sensor networks were initially inspired by military applications, which go from substantial scale acoustic

reconnaissance frameworks for sea observation to little systems of unattended ground sensors for ground target recognition [6]. In any case, the accessibility of low cost sensors and remote correspondence has guaranteed the improvement of an extensive variety of utilizations in both regular citizen and military fields.

## II. LITERATURE SURVEY

In This research paper SuneeK. Gupta and Prasanta K. Jana [7] have proposed hereditary calculation based methodologies for bunching and directing in WSNs. Grouping has been done in their approach in view of leftover vitality of the passages and separation from sensor hubs to their relating bunch head. Likewise directing has been done in their approach in light of the lingering vitality of the passages alongside a tradeoff between transmission separation and number of advances. This proposed calculation has decreased the vitality utilization of the system.

Energy harmonizing is similarly important to delay the network life of WSN. MdAzharuddin and Prasanta K. Jana [8] have proposed PSO-based routing and clustering systems. The routing procedure has been built a trade-off amid energy effectiveness and energy balancing, while the clustering procedure takes care of the energy feasting of gateways as well as SN. They have established an effective particle-encoding system and have resultant a multi-objective fitness purpose for individually of the planned routing and clustering procedures. Their proposed algorithm also tolerated the failure of cluster heads.

The efficiency of WSNs is extremely needy on routing protocols straight touching the net life-time. Clustering is unique of the supreme popular methods preferred in routing processes. Dervis Karaboga et al [9] have proposed artificial bee colony procedure based energy effectual clustering mechanism. ABC algorithm, replicated the intelligent foraging performance of HBS, has been positively used in clustering methods. This proposed algorithm has been improved the lifetime of the network prolong. Their proposed algorithm outperforms the existing algorithms particle swarm optimization and LEACH.

HSA is solitary of the metaheuristics, used to resolve a wide variety of NP-Hard problems. Praveen Lalwani et al [10] have planned Harmony search algorithm for CH selection. The cluster head and routing have been done based on the parameters energy, distance and node degree in their proposed approach. They also have resulting a potential function for the task of non-CH nodes to the CHs. Here some time they, they have proposed a routing algorithm founded on HAS using the same parameters, i.e., energy, node degree and the distance between in the beginning of the fitness function.

Rashmi Ranjan Sahoo et al [11] have presented light weight energetic TRUST prototypical along through honey bee

mating procedure for clustering. This proposed approach prevented malicious node to be a CH. The choice of light weight TRUST prototypical made their clustering technique more secure and energy effectual, which were most essential matters for reserve constrained SN. They have also familiarized a priority arrangement among the trust metrics which was additional realistic. Additionally, the practice of honey bee mating procedure found most suitable node as CH.

To solve such problems having vast examination area, Clustering a network with appropriate load balancing is an NP-hard problematic. optimization procedure is the distinguished possible resolution. Nitin Mittal et al [12] have obtainable clustering procedure for WSNs based on differential evolution known as TEDRP. Double hop communication amongst cluster heads and base station has been used to accomplish load balancing of removed cluster heads and vitality minimization. They likewise considered constancy aware prototypical of TEDRP designation stable TEDRP (STEDRP) with expectation to expand the steadiness time of the system.

## III. PROPOSED TECHNIQUE

We present Energy efficient Gravitational search algorithm (GSA) and Fuzzy based clustering with Hop count based routing for WSN. Contribution of this work is described as follows.

- Cluster formation and cluster head selection are done using the Gravitational search algorithm (GSA).
- Based on fuzzy inference system, Super cluster head (SCH) is selected among the CHs in the network.
- After the cluster formation, efficient route is established based on the hop count of the sensor nodes.

### Issues and challenges in designing WSN:

- Sensor networks don't fit into any normal topology, on the grounds that while sending the sensor hubs they are scattered [8] [9] [10]
- Extremely constrained assets
  - Constrained memory
  - Constrained calculation
  - Constrained power
- It goes under fewer frameworks and furthermore support is exceptionally troublesome.
- unreliable correspondence
  - unreliable information exchange
  - Clashes and inactivity
- Sensor hub depends just on battery and it can't be energized or supplanted. Equipment plan for sensor hub ought to likewise be considered.
- Unattended operations
  - Presentation to physical assault

- Remotely handled
- No focal control point
- Accomplishing synchronization among hubs is likewise another issue.
- Hub failure, topology changes and including of hubs and termination of hubs is another testing issue.
- In view of its transmission nature and antagonistic condition, security is a majorly complicated issue.
- In light of the applications, sensor hub must be selected regarding computation rate.

### Cluster head selection using Gravitational Search Algorithm

Gravitational Search Algorithm performs depend on the gravity law. In GSA, objects are considered as the agents. Due to the force of the gravity, the agents in the region attract each other. So the agents with heavier masses attract the agent with less mass. Thus, masses assist with the support of a straight form of message via GF. Agent with the heavyweight masses that related to optimal resolutions to transfer more gently than lighter ones. Solution of the problems describes the position of the agent or mass. Inertial and gravitational masses are determined with the support of a fitness function. The solution with heavy mass is considered as an optimal solution in the search arena.

Solution of this algorithm is the position of the CHs which are to be selected. Now, let us assume a scheme with  $i^{th}$  agents (masses) i.e.,

$$A_i = [X_{i,1}(t), X_{i,2}(t), \dots, X_{i,D}(t)] \text{ Equation-1}$$

Where  $X_{i,d}(t)$  denotes the site of the  $i^{th}$  negotiator or CHs in the  $d^{th}$  measurement.

The power on the  $i^{th}$  mass from the  $j^{th}$  mass at time  $t$  is well-defined

$$F_{ij}^d(t) = G(t) \times \frac{Mass_{PG_i}(t) \times Mass_{AG_j}(t)}{R_{ij}(t) + \epsilon} \times (x_i^d(t) - x_j^d(t)) \text{ Equation-2}$$

Equation-2

Where  $Mass_{AG_j}(t)$  represents the active gravitational mass associated with the  $j^{th}$  negotiator at time  $t$ .

$Mass_{PG_i}(t)$  denotes the passive gravitational mass associated with the  $i^{th}$  negotiator at time  $t$ .  $\epsilon$  and  $G(t)$  represent a small constant and gravitational constant correspondingly.  $G(t)$  is well-defined as follows

$$G(t) = G_0 \times \exp(-\gamma \times iter / \max iter) \text{ Equation-3}$$

Where,  $\gamma$  and  $G_0$  represents sinking coefficient and primary value correspondingly. Current iteration is represented as  $iter$  and  $\max$  quantity of iteration is

$\max iter$   $R_{ij}(t)$  represents the Euclidian distance amongst the negotiators  $i$  and  $j$ .

By mapping the fitness, the inertial mass of each agent is designed as follows

$$mass_i(t) = \frac{Fit_i(t) - worst(t)}{best(t) - worst(t)} \text{ Equation-4}$$

Where,  $Fit_i(t)$  signifies the suitability rate of the  $i^{th}$  negotiator at time  $t$ . In this work, the fitness significance is intended using the parameters average distance and outstanding energy. the fitness value is derived as An agent with minimum fitness value has heavier mass and has better location, i.e., the improved is the CH selection.

The values  $best(t)$  and  $worst(t)$  are well-defined as

$$best(t) = \min_{j \in \{1, \dots, N\}} Fit_j(t) \text{ Equation-5}$$

$$worst(t) = \max_{j \in \{1, \dots, N\}} Fit_j(t) \text{ Equation-6}$$

Thus, the acceleration of  $i^{th}$  negotiator at time  $t$  is calculated.  $a_i^d(t)$  calculated as

$$a_i^d(t) = \frac{F_i^d(t)}{Mass_i(t)} \text{ Equation-7}$$

The iteration counter is repeated until we obtain the optimal solution.

Nearly Nodes  $n^*(1+\alpha*m)$  are with energy equivalent to the primary energy of a Regular Nodes. In route to maintain the deepest energy feasting in each round within an epoch, the usual amount of CH/round per epoch must be frequent and comparable to  $n^*P_{opt}$ . In the wide-ranging situation the ordinary amount of CH/round per epoch is equivalent to  $n^*(1 + \alpha*m) * P_r$  (for the reason that each virtual Node has the primary energy of a Regular Node). The balanced likelihoods for Regular and Smart Nodes are, correspondingly:

$$P_r = \frac{P_{opt}}{1 + \alpha*m + l*\mu} \text{ Equation -8}$$

$$P_s = \frac{P_{opt}*(1+\alpha)}{1 + \alpha*m + l*\mu} \text{ Equation -9}$$

Here replace  $P_{opt}$  by the one-sided likelihood to get the threshold that is recycled to elect the CH in individually round. We express as  $T_r$  the inception for Regular Nodes and  $T_s$  the threshold for Smart Nodes. Thus, for Regular Nodes,

$$T_r = \begin{cases} \frac{P_r}{1 - P_r * (Cr * mode \frac{1}{P_r})} & \text{if } n_r \in G' \\ 0 & \text{otherwise} \end{cases} \text{ Equation -10}$$



$$T_s = \begin{cases} \frac{P_s}{1 - P_s * (Cr * mode \frac{1}{P_s})} & \text{if } n_s \in G'' \\ 0 & \text{otherwise} \end{cases} \quad \text{Equation -11}$$

$G'$  &  $G''$  are the established of Regular Nodes and usual of Smart Nodes that has not turn into CHs in the last  $\frac{1}{P_s}$  respectively, so ensuring that the equations 3 and 4 are working for sequences of the epoch, and  $T_s$  threshold applied to a numbers of  $n*m$  Smart Nodes. This assurance that respectively Smart Node will turn into a CH accurately once each  $\frac{1}{P_{opt}} * \frac{1+\alpha*m}{1+\alpha}$  rounds. Let us define this period as sub-epoch.

Node  $N$  start sending Advertisement Packet to destination  
Check destination average distance from source through equation -1

$$d_{ev} = \sum_1^N d(i) \quad \text{Equation -12}$$

Where  $i=1,$

Compute  $T_{time}$

Where  $T_{time}$  is transmitting time interval of a packet from source to destination

Find Neighbor Discovery

Identify nonstop value

Calculate Optimal Probability of Nodes  $P_{opt}$

Make clusters base on energy of Nodes (by equation 3,4),  $P_r$ , and  $P_s$

Initialize the Agents i.e.,  $m$  number of CHs.

Estimate the fitness function for individually negotiator using (10).

Bring up-to-date  $G(t)$ , best  $(t)$  & worst  $(t)$  using (3), (5) and (6) respectively.

Compute the total force consuming (1).

Compute inertial mass and acceleration using (4) and (7) respectively.

Update velocity and position using.

Process continued until get the optimal solution.

The agent with optimal solution is selected as a number of CHs.

Calculate Threshold Sensitive Value (by equation 10, 11)  $T_r$ , and  $T_s$

Every Node Generate value  $Ngv$

If  $T_r > Ngv$

Reg. Nodes Become CH ( $G'$ )

Else if  $T_s > Ngv$

Smart Nodes Become CH ( $G''$ )

Else

Re-Calculate  $Ngv$  Until Node Energy  $\leq 0$

End if

Calculate Average no. of CH per Round ( $Cr$ ) by equation 7

Algorithm Periodic Updates

Identify nonstop value ( $AT$  and  $DAT$ ) Value  $Int$

$Int =$  store new value

If  $AT \geq T_r$  Or  $Int_x \geq Int_y$ ,

Transmitter ON

Else if  $AT \geq T_s$  Or  $Int_x \geq Int_y$ ,

Transmitter ON

Else

Transmission will decreased

End if

Repeat until node died.

Nodes Sleeping until not identify greater than  $Int$  or Active Threshold value

## IV. CONCLUSION

The main finding of this research of routing protocols for WSNs are energy organization, network lifespan optimization and the constancy age. This study paper proposed "A Gravitational Energy Sensitive Energy Hierarchical Protocol" (GESEHP) protocol technique in which every sensor node has energy levels of heterogeneity ordered network which autonomously selects himself as a CH based on its primary energy relative to that of other nodes. The energy ingestion of CHs is further abridged by threshold-based inter cluster data broadcast algorithm. Also, dual-hop message is employed to improve the load complementary and to minimize the energy ingestion of the distant CHs. To equilibrium the energy ingestion in the network, an auction appliance was accessible to the cluster formation procedure, which helps the SN with low energy to extend their lives. cluster members join the cluster head based on distance and cluster head degree to utilize the energy efficiently and to extend the network lifetime. Also considering the detection errors, an improved trilateration technique was used to development high localization accuracy for the goal tacking. Through simulations using MATLAB, the proposed algorithm is evaluated. This work is settled that our protocol GESEHP will attain improved results in minor as well as bulky sized networks. So from it is clear that our planned protocols GESEHP will be superior than all other protocols discussed.

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